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*Non-preemptive scheduling algorithms and
schedulability conditions for real-time systems with
precedence and latency constraints*

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Non-preemptive scheduling algorithms and schedulability conditions for real-time systems with precedence and latency constraints

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Abstract: First we justify our concern in latency constraints for real-time systems with precedence constraints. We evoke the model based on graph theory used to state and solve the problem of non-preemptive scheduling systems with precedence and latency constraints. Because latency constraints involve pairs of operations related to the graph which models the precedence constraints we define three relations between pairs of operations relations which determine the way of scheduling the operations. We give necessary and sufficient condition of schedulability for the particular case of systems with precedence and latency constraints where all pairs on which latency constraints are imposed are in one of these relations. Finally we give general schedulability condition for real-time systems with precedence and latency constraints and we propose scheduling algorithm which is proved optimal.

Key-words: real-time graphs scheduling schedulability algorithms complexity mono-processor

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Ordonnancement non-préemptif et conditions d'ordonnançabilité pour systèmes temps réel avec contraintes de précédences et de latences

Résumé : On commence par justifier notre intérêt pour les contraintes de latences pour des systèmes temps réel avec contraintes de précédences. On rappelle notre modèle utilisant les graphes afin de poser et de résoudre le problème d'ordonnancement non-préemptif de systèmes avec contraintes de précédences et de latences. Puisque les contraintes de latence sont imposées sur des paires d'opérations du graphe qui définit les contraintes de précédence on définit trois relations entre paires d'opérations relations qui déterminent la manière dont les opérations vont être ordonnées. On donne une condition nécessaire et suffisante d'ordonnançabilité pour le cas des systèmes avec contraintes de précédences et de latences où les paires avec contraintes de latences sont en une de trois relations. Finalement on donne une condition générale d'ordonnançabilité et on propose un algorithme d'ordonnancement qui est prouvé optimal.

Mots-clés : temps réel graphes ordonnancement ordonnançabilité algorithmes complexité monoprocesseur

1 Introduction

Real-time systems are first of all reactive systems [1] that is to each event arriving in the system through sensors corresponds an output event produced through actuators to the environment in reaction to this input event. The arrival of input events is indefinitely repeated and an output event is obtained from one or several input events after several operations on which precedence constraints may be imposed. For example in the case of brake control in a car when the driver presses the brake pedal the wheels must stop before a fixed delay corresponding to the execution of control laws relating “pedal-press” event and “wheels-stop” event. We call this constraint *latency* constraint. This type of delay was already used by the real-time community but either the models took into account only one global latency constraint [2–3] or the delay may be imposed only on sensors and actuators [4]. This paper generalises these results allowing to have several latency constraints which are not imposed only on sensors and actuators but also on the operations which are necessary to obtain output events from input events. For example it is possible to specify the brake system of a car (figure 1) by graph where *PRESS* represents sensor giving the information which indicates that the driver presses the brake pedal *SPEED* represents sensor giving the wheel speed *DEAC* represents the deactivation of the speed regulator *ESTIM* represents the estimation of the pressure on the brake pedal *ABS* represents the anti-locking brake system (ABS) and *BRAKE* represents the actuator giving the pressure on the brake wheels. We may need to impose a delay between *PRESS* and *BRAKE* and another delay between *DEAC* and *BRAKE*.

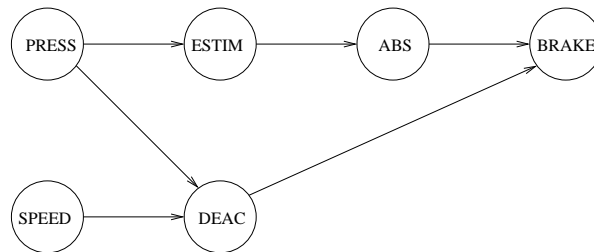


Figure 1 Example of brake control

In this paper we study the non-preemptive case and we plan to extend subsequently the results to the preemptive case evaluating its overhead.

The next section gives some notations and existing results for systems with precedence constraints. Section 3 presents our model given in [5]. In this section we define the latency constraint. In the following section we give a schedulability condition for real-time systems with precedence and latency constraints. Section 5 presents an optimal scheduling algorithm. The last section concludes and proposes future work.

2 Notations and existing results

In order to clearly distinguish the specification level from the implementation level we use the term *operation* instead of the commonly used “task” too closely related to the implementation level and in turn we use the term *operator* instead of “processor” or “machine”.

For an operation A we may specify computation time $C_{\mathbf{A}}$ deadline $D_{\mathbf{A}}$ (defined from the start of the schedule) and start time $s_{\mathbf{A}}$. Also for pairs of operations we may specify precedence constraints that may be represented by a directed cyclic graph where the vertices are the operations and the edges are the precedence constraints.

We evoke now some main results on systems with precedence constraints and deadlines in the case of one operator. For the non-preemptive problem with precedence constraints minimising a monotone function which allows to define deadlines Lwiler gives the optimal “first-to-last-rule” [6]. Also for the non-preemptive problem with precedence and deadlines Blazewicz gives a polynomial solution [7]. For the preemptive problem with precedence constraints and deadlines there are results on the schedulability of a system [8] [9] [10] and [11].

In this paper we give a schedulability condition for real-time systems with precedence and latency constraints using the model proposed in [5].

3 Model for systems with precedence and latency constraints

In our model a system with precedence constraints is defined by an infinite directed graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ where \mathcal{V} is the set of operations and \mathcal{E} the set of edges which represents the precedence constraints between operations. Because a real-time system is reactive we model the system by an infinite graph issued from an infinite repetition of a finite subgraph called “pattern” [3]. If one considers only the pattern itself according to its partial order the first operations are called inputs and the last operations are called outputs. These operations correspond to respectively sensors and actuators. The edges between operations belonging to the same pattern are called intr-pattern and the edges between operations belonging to different patterns are called extr-pattern. For example in figure 2 the edge from A to B is an intr-pattern edge and the edge from D belonging to the i^{th} pattern to A belonging to the $(i+1)^{\text{th}}$ pattern is an extr-pattern. The infinite repetition of the pattern of the graph induces an infinite repetition of all the operations.

Definition 1 [12] *A directed path from A_1 to A_n is a alternating sequence $A_1(A_1, A_2)A_2 \dots (A_{n-1}, A_n)A_n$ of vertices and distinct edges, where $A_i \in \mathcal{V}$ and $(A_i, A_{i+1}) \in \mathcal{E}$, $i = 1, 2, \dots, n$.*

For the sake of simplicity and because we use only directed graphs from now on we will use the term path instead of directed path.

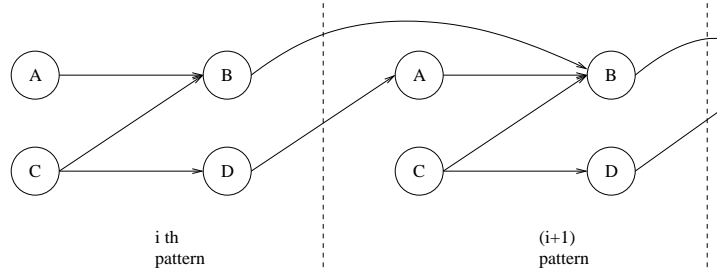


Figure 2 System of operations defined by infinite directed graph

We denote by \mathcal{P} the set of all paths of graph and we say that $P(A, B) \in \mathcal{P}$ if there is the shortest path from A to B . If $\nexists P(A, B) \in \mathcal{P}$ then there is no path from A to B . If there is the shortest path from A to B we denote by $\mathcal{M}(A, B)$ the set of all operations belonging to all the paths from A to B $\mathcal{M}(A, B) = \{C \mid P(A, C) \in \mathcal{P} \text{ and } P(C, B) \in \mathcal{P} \cup \{A, B\}$. In order to illustrate the latter notation we give the following example.

Example 1 Let be the graph given by figure 3. The set $\mathcal{M}(A, G) = \{A, B, D, C, G\}$ is not empty because there is the shortest path from A to G and we have $P(A, G) \in \mathcal{P}$. For example, from A to G there are four paths: $A(A, D)D(D, G)G$, $A(A, B)B(B, D)D(D, G)G$, $A(A, D)D(D, C)C(C, G)G$ and $A(A, B)B(B, D)D(D, C)C(C, G)G$. On the contrary the set $\mathcal{M}(C, E)$ is empty because there is no path from C to E .

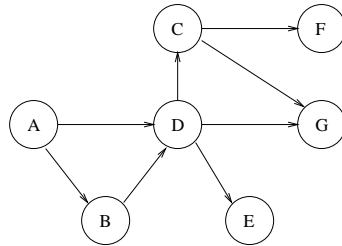


Figure 3 Set of operations belonging to all paths from A to G

Definition 2 For system of operations, schedule S is total ordered set of start times of all the operations $S = \{s_A \in \mathbb{N}, A \in \mathcal{A}\}$ such that the precedence constraints are satisfied. We denote by \mathcal{S} the set of all schedules.

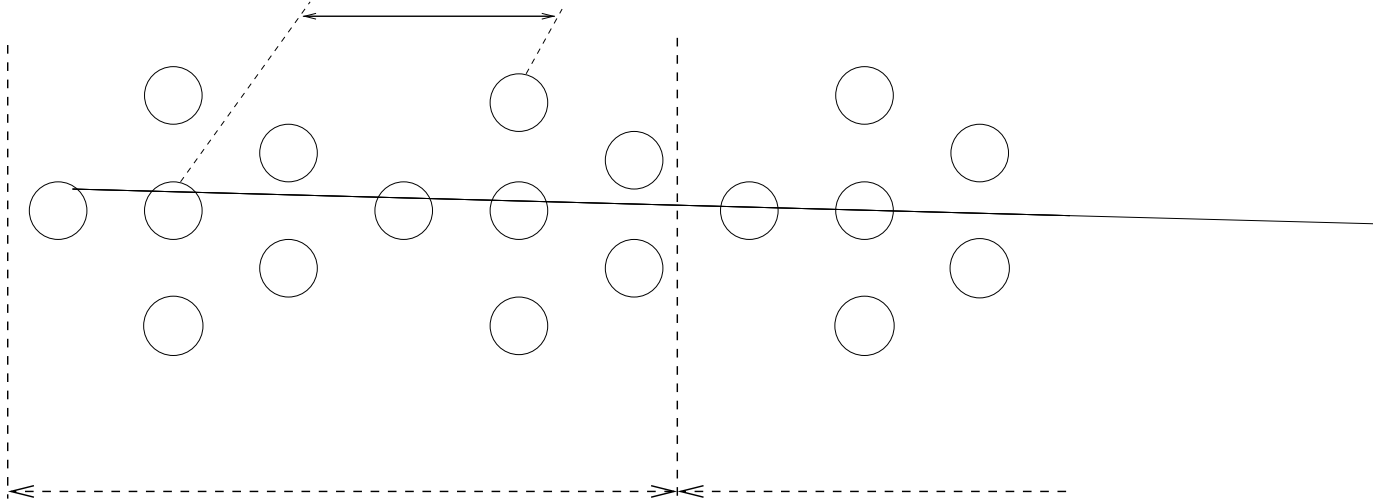
Remark 1 An operation is available when all its predecessors are scheduled. We consider schedules without idle time, i.e. we schedule available operations at the end of the last scheduled operation and we have $A, B \in \mathcal{A}$ such that $s_A + C_A = s_B$.

The edges of the system of operations define a partial order on the set of operations. There are several total orders which may be obtained from this partial order. Because a schedule is a total order on the set of operations with a start time associated to each operation then we may have several schedules for the same system of operations.

Remark 2 The directed pair of operations $(A, B) \in \mathcal{E}$ implies that B must be scheduled, only if A was already scheduled, and we have $s_A + C_A \leq s_B$, where $s_A, s_B, C_B \in \mathbb{N}^+$.

Definition 3 [5] on a pair of operations (A, B) with $P(A, B) \in \mathcal{P}$ and A and B belonging to the same pattern, we say that a latency constraint $L(A, B)$ is imposed if the operations are scheduled such that $s_B + C_B \leq s_A + L_{AB}$, $L_{AB} \in \mathbb{N}^+$. Let \mathcal{L} be the set of all latency constraints imposed for a system.

Remark 3 The condition imposing to A and B to belong to the same pattern is not restrictive. If we want to impose a latency constraint on two operations which do not belong to the same pattern, then it is sufficient to define a new pattern. Indeed because the value of a latency constraint is finite (otherwise it does not define a real-time constraint) we will never obtain a finite pattern. The figure 4 gives such an example. We want to define the latency constraint $L(C, B)$ with C and B belonging to two different patterns. Therefore we choose a new pattern containing two old patterns.



Definition 4 *if there is a schedule for a system of operations which satisfies all the precedence constraints then the system is called schedulable.*

The definition generalises the notion of precedence constraint for two operations which are not necessarily input and output operations.

4 Schedulability condition

We give a necessary and sufficient condition for a system with precedence and precedence constraints to be schedulable. Because the graph is a pattern infinitely repeated and the precedence constraints are imposed on operations belonging to the same pattern studying only the pattern is enough to obtain the schedulability condition.

The precedence constraints are imposed on pairs of operations related by a path which imposes a total order on the operations belonging to this path. So if we want to schedule a system of operations with precedence constraints we study the existence of paths between pairs of operations with precedence constraints. Consequently in this section first we present relations between two pairs of operations relative to scheduling. For these pairs on which precedence constraints are imposed we present a schedulability condition.

For the sake of simplicity we call “an operation belonging to a pair (X, Y) ” an operation belonging to the last one of the paths from X to Y . Also we say that “a pair (X, Y) contains an operation Z ” when Z belongs to the pair (X, Y) .

For some pair of operations (X, Y) belonging to a system and a schedule of this system we call “schedule length” the time between the start of an operation X and the end of an operation Y . We denote this time by $\delta_{XY}(S) = s_Y + C_Y - s_X$ where $s_X, s_Y \in S$. Without any loss of generality we consider that X is always scheduled before Y .

Because we consider that the available operations are scheduled at the end of the last scheduled operation (see remark 1) we have $\delta_{XY}(S) = \sum_{\forall C; s_X \leq s_C \leq s_Y} C_C$.

Theorem 1 *Let $G = (V, E)$ be a graph defining a system and $L(A, B)$ a precedence constraint where $A, B \in V$. If the system is schedulable then the sum of the execution times of operations belonging to $\mathcal{M}(A, B)$ is smaller or equal to $L_{A;B}$.*

Proof If the system is schedulable then there is a last schedule S satisfying all constraints of the system. So for a schedule S we have

$$\delta_{AB}(S) \leq L_{A;B} \quad (1)$$

Because of the partial order the operations belonging to $\mathcal{M}(A, B)$ must be scheduled between A and B and we have $\sum_{C \in \mathcal{M}(A;B)} C_C \leq \delta_{AB}(S) \leq L_{A;B}$. So $\sum_{C \in \mathcal{M}(A;B)} C_C \leq L_{A;B}$. The theorem is proved \square

The theorem 1 gives a necessary condition for a precedence constraint to be satisfied. By imposing this condition we guarantee that we can always schedule between the first and

the last operation of ℓ tency constraint ℓ the last the operations belonging to this ℓ tency constraint.

If between these operations there is no operation belonging to another π ir on which ℓ tency constraint is imposed then this condition is also sufficient (see theorem 2). This is possible because all schedules satisfying the partial order defined by graph for which we obtain the smallest time between the first and the last operation of the ℓ tency constraint contain only operations belonging to the π ir on which the ℓ tency constraint is imposed. All these schedules lead to the same set of operations scheduled between the first operation and the last operation of the ℓ tency constraint set that we call “minimal set corresponding to the ℓ tency constraint”.

On the contrary if between these operations there is at least one operation belonging to another π ir on which ℓ tency constraint is imposed then the condition given by theorem 1 is only necessary (see theorem 5). This is possible because all schedules satisfying the partial order defined by graph for which we obtain the smallest time between the first and the last operation of the ℓ tency constraint may contain also operations belonging to another π ir on which ℓ tency constraint is imposed. All these schedules lead to different sets of operations scheduled between the first operation and the last operation of the ℓ tency constraint sets that we call “minimal sets corresponding to the ℓ tency constraint”.

The first consequence of these interpretations of theorem 1 is the corollary 1 concerning the case of system with only one ℓ tency constraint. So we are in the case of ℓ tency constraint imposed on π ir which does not contain any operation belonging to another π ir on which ℓ tency constraint is imposed and the condition given by theorem 1 is necessary and sufficient.

Corollary 1 *Let $\text{system} = (\text{graph}, \mathcal{E})$ be graph defining system and (A, B) the only ℓ tency constraint of the system. The system is schedulable if and only if the sum of execution times of operations belonging to $\mathcal{M}(A, B)$ is smaller or equal to $L_{\mathbf{A};\mathbf{B}}$.*

Proof If we have only one ℓ tency constraint then studying the schedulability of the system amounts to consider all schedules satisfying the partial order and containing between the first and the last operation of the ℓ tency constraint only operations belonging to the π ir on which the ℓ tency constraint is imposed. Indeed for these schedules we obtain the smallest time between the first and the last operation of the ℓ tency. Consequently it is sufficient to compare the sum of execution times of operations belonging to the π ir to value of the ℓ tency constraint. The corollary is proved \square

Example 2 *This example illustrates the case of one ℓ tency constraint. For the graph given in figure 5 we consider the ℓ tency constraint $L(A, D)$. We consider all execution times equal to 1. The minimal set $\{A, B, C, E, D\}$ contains between the first and the last operation of the ℓ tency constraint only operations belonging to the π ir on which the ℓ tency constraint is imposed. The operation F does not belong to this set. The system is schedulable if and only if the value of the ℓ tency constraint is greater than 5.*

4.1 Relations between two pairs of operations relatively to scheduling

We consider two pairs of operations and we study the case where they are connected or not by paths. The paths which connect two pairs are those who start from an operation belonging to one of the pairs to an operation belonging to the other pair.

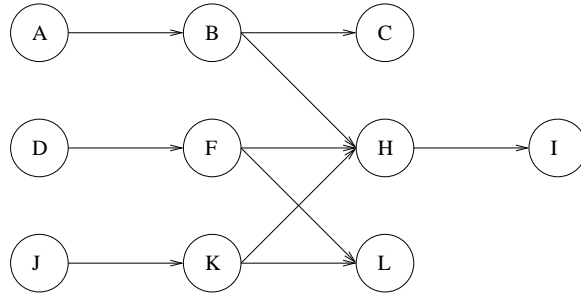


Figure 6 Example of relations between pairs of operations

Thus for two pairs of operations we have 2^2 possible combinations covered by the three following cases

1. there is no path from an operation belonging to one of the pairs between the considered pair to an operation belonging to one of the pairs between the other pair (for example pairs (A, C) and (J, L) of figure 6). This relation is called \parallel ;
2. there is at least a path from one pair to the other one and there is no path from the latter pair to the first one or vice versa (for example pairs (A, C) and (D, I) of figure 6). This relation is called Z . Note that it covers two cases;
3. there is at least a path from one pair to the other one and vice versa (for example pairs (D, I) and (J, L) of figure 6). This relation is called X .

In the case of relation \parallel (see figure 6) no precedence constraint imposes to an operation belonging to $\mathcal{M}(A, C)$ to be scheduled before or after all operations belonging to $\mathcal{M}(J, L)$. For example the schedules with A, B and C scheduled before J, K and L or vice versa satisfy the partial order.

In the case of relation Z (see figure 6) the precedence constraints impose to operations belonging to $\mathcal{M}(A, B)$ to be scheduled before operation belonging to $\mathcal{M}(H, I)$. However they do not impose any order between operations belonging to $\mathcal{M}(B, C)$ B and operations belonging to $\mathcal{M}(D, H)$ H . For example A, B and C may be scheduled before all operations belonging to $\mathcal{M}(D, I)$ and similarly D, F, H and I may be scheduled before all operations belonging to $\mathcal{M}(A, C)$.

In the case of relation X (see figure 6) the precedence constraints impose to operations belonging to $\mathcal{M}(D, F)$ to be scheduled before operations belonging to $\mathcal{M}(L, L)$ and to operations belonging to $\mathcal{M}(H, I)$ to be scheduled before operations belonging to $\mathcal{M}(J, K)$. However they do not impose any order between operations belonging to $\mathcal{M}(D, F)$ and operations belonging to $\mathcal{M}(J, K)$. For example D and F may be scheduled before or after J and K and H and I must be scheduled after J and K and vice versa.

By taking into account the relations between pairs of operations we study the schedulability condition for latency constraints imposed on pairs in relation Z and/or in relation \parallel . We study the schedulability condition for latency constraints imposed on pairs in relation X . Finally we give a general schedulability condition for latency constraints imposed on pairs in relation \parallel , Z and X .

4.2 Relations \parallel and Z

We study the schedulability of systems with latency constraints imposed on pairs in relation Z and/or in relation \parallel . For example in figure 7 we have three latency constraints $L(A, C)$, $L(D, I)$ and $L(J, L)$ imposed on pairs in relation Z and/or in relation \parallel .

Only the relation Z imposes a partial order on pairs where the relation \parallel does not impose any order. For example the partial order imposes only to A and to B to be scheduled before H and I .

The schedulability studies search among all possible schedules those leading to minimal sets corresponding to latencies. The lemma 1 allows to find those schedules and lemma 2 proves that for pairs in relation \parallel and in relation Z those minimal sets are identical. Consequently even if relatively to the partial order the two cases are not identical relatively to the schedulability they are. This implies that we may give a unique schedulability condition for the two relations. This condition is given by theorem 2 which ends this subsection.

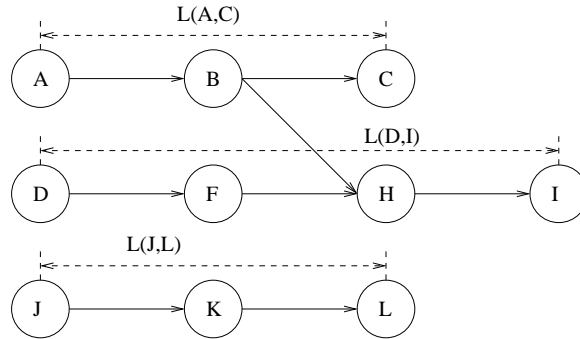


Figure 7 Latency constraints

Lemma 1 Let A, B be two operations belonging to a system given by $graph = (\mathcal{P}, \mathcal{E})$, such that $P(A, B) \in \mathcal{P}$. We denote by S a schedule such that $H \in \mathcal{M}(A, B)$, either we have $s_H + C_H < s_A + C_A$, or we have $s_B + C_B < s_H + C_H$. If \mathcal{S}' is the set of the schedules S' such that $H \in \mathcal{M}(A, B)$ with $s'_A + C_A < s'_H + C_H < s'_B + C_B$, then $\delta_{AB}(S) = \delta_{AB}(S')$, $S' \in \mathcal{S}'$.

Pr oof Because S is a schedule such that $H \in \mathcal{M}(A, B)$ either we have $s_H + C_H < s_A + C_A$ or we have $s_B + C_B < s_H + C_H$ only operations belonging to $\mathcal{M}(A, B)$ are rescheduled from s_A to s_B and we have

$$\delta_{AB}(S) = \sum_{I \in \mathcal{M}(A; B)} C_I \quad (2)$$

For some schedule $S' \in \mathcal{S}'$ let $N = H$ such that $H \in \mathcal{M}(A, B)$ and $s'_A + C_A < s'_H + C_H < s'_B + C_B$. We have

$$\delta_{AB}(S') = \sum_{I \in \mathcal{M}(A; B)} C_I + \sum_{H \in N} C_H, \quad S' \in \mathcal{S}' \quad (3)$$

By subtracting the equations (2) and (3) we obtain $\delta_{AB}(S') - \delta_{AB}(S) = \sum_{H \in N} C_H = 0$, $S' \in \mathcal{S}'$. Finally we have $\delta_{AB}(S) = \delta_{AB}(S') = S' \in \mathcal{S}'$. The lemma is proved \square

Lemma 2 For four operations A, B, C and D , if $(A, B) \parallel (C, D)$ or if $(A, B) \mathbf{Z} (C, D)$ then we have $\mathcal{M}(A, B) \cap \mathcal{M}(C, D) = \emptyset$.

Pr oof We prove by contradiction that if $(A, B) \mathbf{Z} (C, D)$ then $\mathcal{M}(A, B) \cap \mathcal{M}(C, D) = \emptyset$. We suppose that $F \in \mathcal{M}(A, B) \cap \mathcal{M}(C, D)$. Because $F \in \mathcal{M}(A, B)$ respectively $F \in \mathcal{M}(C, D)$ we have

$$P(A, F) \in \mathcal{P} \quad (4)$$

and

$$P(F, B) \in \mathcal{P} \quad (5)$$

respectively

$$P(C, F) \in \mathcal{P} \quad (6)$$

and

$$P(F, D) \in \mathcal{P} \quad (7)$$

From (4) and (7) respectively from (5) and (6) we obtain $P(A, D) \in \mathcal{P}$ and $P(C, B) \in \mathcal{P}$. This is in contradiction with the definition of relation \mathbf{Z} which says that there is at least one path from a processor to the other processor and there is no path from the last processor to the first processor. We have a contradiction so the supposition that there is $F \in \mathcal{M}(A, B) \cap \mathcal{M}(C, D)$ is not true and we have $\mathcal{M}(A, B) \cap \mathcal{M}(C, D) = \emptyset$.

The proof for the case of relation \parallel is similar to the case of relation \mathbf{X} . The lemma is proved \square

The lemma 2 proves that l-tency constraint $L(A, B)$ in relation \parallel or in relation Z with another l-tency constraint $L(C, D)$ does not contain any operation belonging to this latter constraint ($\mathcal{M}(A, B) \cap \mathcal{M}(C, D) = \emptyset$). This implies that each minimal set corresponding to l-tency constraint contains only operations belonging to this constraint so for the two cases the minimal set corresponding to each l-tency constraint is identical.

Theorem 2 Let $\mathcal{G} = (G, \mathcal{E})$ be a graph defining a system and each two periods, on which l-tency constraints are imposed, are either in relation \parallel , either in Z . A schedule satisfies all the l-tency constraints if and only if $\sum_{H \in \mathcal{M}(A;B)} C_H \leq L_{AB}$, for all A and B having l-tency constraint.

Proof The lemma 1 shows that for two operations A and B related by a path scheduling only operations which belong to $\mathcal{M}(A, B)$ between A to B will decrease the value of $\delta_{AB}(\cdot)$. This means that if a schedule in which only operations which belong to $\mathcal{M}(A, B)$ are scheduled between A to B do not satisfy l-tency constraint L_{AB} then no other schedule will. Therefore and because $\mathcal{M}(A, B) \cap \mathcal{M}(C, D) = \emptyset$ for all periods which are in relation \parallel or in relation Z (lemma 1 and lemma 2) from now on we will consider only schedules of this type.

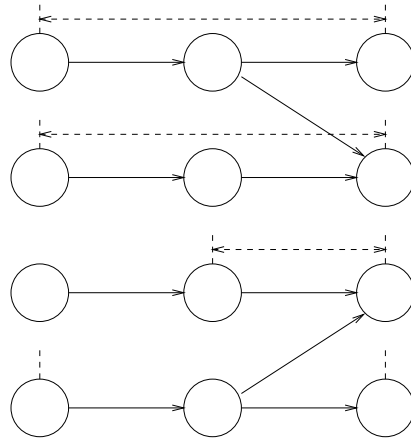
A schedule S satisfies all the l-tency constraints if and only if $\delta_{AB} \leq L_{AB}$ A and B having l-tency constraint (definition 3). Because $H \in \mathcal{M}(A, B)$ either we have $s_H + C_H < s_A + C_A$ or we have $s_B + C_B < s_H + C_H$ then a schedule S satisfies all the l-tency constraints if and only if $\sum_{H \in \mathcal{M}(A;B)} C_H \leq L_{AB}$ for all A and B having l-tency constraint. The theorem is proved \square

Remark 4 When the l-tency constraints are in relation \parallel or in relation Z , the minimal set corresponding to l-tency constraint is equal to the set of operations belonging to this l-tency constraint. The first part of example 3 illustrates this kind of set.

Example 4 This example illustrates the schedulability condition for a system of operations with l-tency constraints in relation \parallel or in relation Z . For the graph given in figure we consider the l-tency constraints $L(A, C)$, $L(D, F)$, $L(H, I)$ and, respectively, $L(J, L)$ imposed on periods (A, C) , (D, F) , (H, I) and, respectively, (J, L) . All l-tency constraints are equal to 3 and $C_A = 1$, $A = 1$. We notice that all periods are either in relation \parallel , either in relation Z . The schedulability condition implies that l-tencies must be greater than the sum of execution times of operations. We suppose that this condition is satisfied so there is at least one schedule which satisfies every constraint of the system. Figure 9 gives such a schedule.

4.3 Relation X

In order to present the results concerning systems with l-tency constraints imposed on periods in relation X we introduce two new notations.



Let $(A, B), (C, D)$ with $P(A, B), P(C, D) \in \mathcal{P}$ be some pairs in relation X . Each pair has operations which must be scheduled before operations belonging to the other pair. Like in the previous case of pairs in relation \parallel and/or in relation Z the schedulability studies for pairs in relation X are based on minimal sets corresponding to the lency constraints.

For two pairs in relation X ft denotes set of operations which are first on all paths between the first operation of pair and those operations complementary to the existence of the step from one pair to these operations.

We denote by $ft_{\mathbf{CD}}(A, B)$ the set of operations $E \in \mathcal{M}(A, B)$ for which $F \in \mathcal{M}(C, D)$ such that $P(F, E) \in \mathcal{P}$ and $\nexists G \in \mathcal{M}(A, B)$ for which $F \in \mathcal{M}(C, D)$ such that $P(F, G) \in \mathcal{P}$. This means that $ft_{\mathbf{CD}}(A, B)$ is the set of operations E belonging to one of the paths from A to B such that there is a path to E from one of the operations belonging to one of the paths from C to D and there is no operation G belonging to one of the paths from A to B such that there is a path to G from one of the operations belonging to one of the paths from C to D . We denote by $\Gamma_{\mathbf{CD}}^-(A, B)$ the set of predecessors of $ft_{\mathbf{CD}}(A, B)$ i.e. the set of operations E for which there is an operation $F \in ft_{\mathbf{CD}}(A, B)$ such that $(E, F) \in \mathcal{E}$.

For two pairs in relation X lt denotes set of operations which are last on all paths between those operations and the last operation of pair and complementary to the existence of the step from these operations to the pair.

We denote by $lt_{\mathbf{CD}}(A, B)$ the set of operations $E \in \mathcal{M}(A, B)$ for which $F \in \mathcal{M}(C, D)$ such that $P(E, F) \in \mathcal{P}$ and $\nexists G \in \mathcal{M}(A, B)$ for which $F \in \mathcal{M}(C, D)$ such that $P(G, F) \in \mathcal{P}$. This means that $lt_{\mathbf{CD}}(A, B)$ is the set of operations E belonging to one of the paths from A to B such that there is a path from E to one of the operations belonging to one of the paths from C to D and there is no operation G belonging to one of the paths from E to B such that there is a path from G to one of the operations belonging to one of the paths from C to D . We denote by $\Gamma_{\mathbf{CD}}^+(A, B)$ the set of successors of $lt_{\mathbf{CD}}(A, B)$ i.e. the set of operations E for which there is an operation $F \in lt_{\mathbf{CD}}(A, B)$ such that $(F, E) \in \mathcal{E}$.

Example 5 In order to illustrate these notions we give the following example. In figure 10, for $(A, B) \times (C, D)$, we have $ft_{\mathbf{CD}}(A, B) = \{F, G\}$, $lt_{\mathbf{CD}}(A, B) = \{G\}$, $ft_{\mathbf{AB}}(C, D) = \{G\}$ and $lt_{\mathbf{AB}}(C, D) = \{G, I\}$.

The schedulability study is based on minimal set belonging to lency constraint L_1 which must be scheduled before the last operation of another lency constraint L_2 with $L_1 \times L_2$. We study in schedule the position of operations belonging to L_1 which only increase the schedule length between the first operation and the last operation of L_2 without modifying the schedule length between the first operation and the last operation of L_1 once the first operations or the last operations were scheduled.

For example in figure 11 we consider that L_1 is lency constraint on pair (A, B) and that L_2 is lency constraint on pair (C, D) . If we schedule A before C then for all positions of operation E in the schedule the schedule length between A and B stays identical. On the contrary the position of E is important for the other pair (C, D) . If we schedule E after C we only increase the schedule length between C and D .

Similarly in figure 12 we consider that L_1 is the lency constraint on pair (A, B) and that L_2 is lency constraint on pair (C, D) . If we schedule B before D then the position of

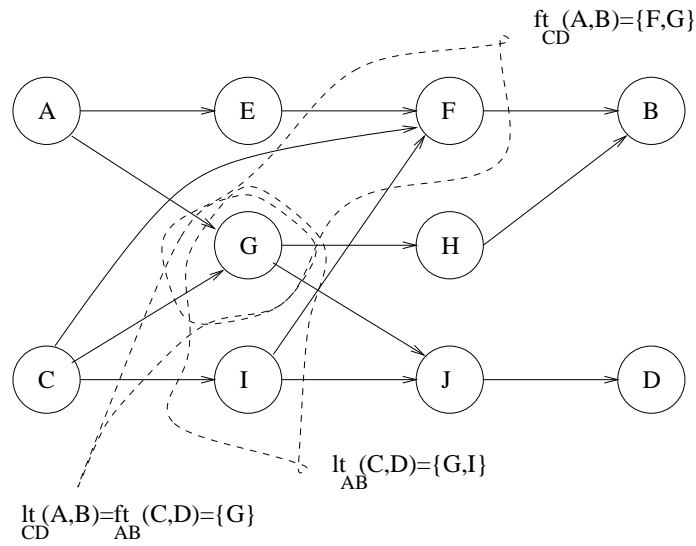


Figure 10 Example for ft and lt

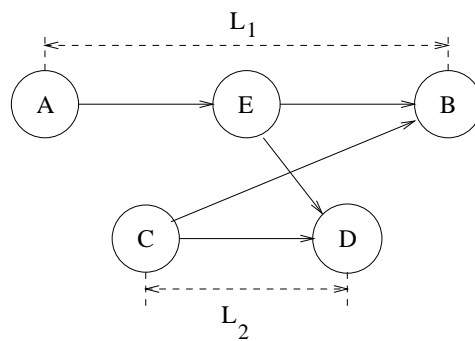


Figure 11 Operations only increasing the schedule length which respect the beginning of latency constraint

operation F in the schedule is not important for the pair (C, D) because the schedule length time between C and D stays identical. On the contrary the position of F is important for the other pair (A, B) because if we schedule F before B we increase the schedule length between A and B .

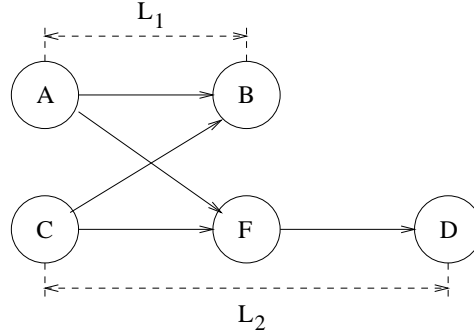


Figure 12 Operations only increasing the schedule length which respect the end of latency constraint

Theorem 3 Let $\mathcal{G} = (\mathcal{H}, \mathcal{E})$ be a graph defining a system and there are two latency constraints imposed on pairs (A, B) and (C, D) , where $(A, B) \times (C, D)$ and $L_{AB} = \sum_{H \in \mathcal{M}(A;B)} C_H$. The system is schedulable if and only if $L_{CD} \leq \sum_{H \in \mathcal{M}(A;B) \cup \mathcal{M}(C;D)} C_H$.

Proof Because $L_{AB} = \sum_{H \in \mathcal{M}(A;B)} C_H$ then we may schedule between the operation A and the operation B only operations belonging to $\mathcal{M}(A, B)$. So no operation belonging to $\mathcal{M}(C, D)$ and not belonging to $\mathcal{M}(A, B)$ can be scheduled between A and B .

Consequently when C and D do not belong to $\mathcal{M}(A, B)$ these operations must be scheduled before A and after B which implies that all operations belonging to $\mathcal{M}(A, B)$ are scheduled between C and D . And then we have $L_{CD} \leq \sum_{H \in \mathcal{M}(A;B) \cup \mathcal{M}(C;D)} C_H$. The theorem is proved \square

Remark 5 In theorem 3 we do not take into account the trivial case where C and D belong to $\mathcal{M}(A, B)$. Indeed if C and D belong to $\mathcal{M}(A, B)$, then all operations belonging to $\mathcal{M}(C, D)$ belong also to $\mathcal{M}(A, B)$. So, the latency constraint imposed on (A, B) must be at least greater or equal to the sum of execution times of operations belonging to $\mathcal{M}(A, B)$.

Remark 6 For the case studied by theorem 3 the minimal set of the latency constraint (A, B) is equal to the set of operations belonging to the latency constraint. For the same case, the minimal set of the latency constraint (C, D) is equal to the set of operations belonging to the two latency constraints. For example in figure 6 if we consider the latency constraint $L(D, I)$ is equal to the sum of execution times of operations belonging to $\mathcal{M}(D, I)$ then the

minimal set of the constraint (D, I) is equal to $\{D, F, H, I\}$ and the minimal set of the constraint (J, L) is equal to $\{J, K, L, D, F, H, I\}$.

The two properties concerning the position of the first and the last operations of two constraints are proved by lemma 3 and lemma 4. The theorem 5 which follows the two lemmas uses it for the case where all lency constraints are in relation X .

Lemma 3 We have system given by graph $G = (V, E)$ such that all paths, on which lency constraints are imposed, are in relation X . For $(A, B) X (C, D)$ and some schedule S with $s_A \prec s_C$, if all operations $E \in \bigcup_{H \in \Gamma_{CD}^-(A;B)} \mathcal{M}(A, H)$ are scheduled between

s_A and s_C , then $\delta_{AB}(S)$ is not modified compared with the case when the last operation $E \in \bigcup_{H \in \Gamma_{CD}^-(A;B)} \mathcal{M}(A, H)$ is scheduled after s_C . Also, if the last operation $E \in \bigcup_{H \in \Gamma_{CD}^-(A;B)} \mathcal{M}(A, H)$ is scheduled after s_C , then $\delta_{CD}(S)$ is increased compared with the case

when all operations $E \in \bigcup_{H \in \Gamma_{CD}^-(A;B)} \mathcal{M}(A, H)$ are scheduled between s_A and s_C .

Proof Because $E \in \bigcup_{H \in \Gamma_{CD}^-(A;B)} \mathcal{M}(A, H)$ and $\mathcal{M}(A, B)$ E is always scheduled between s_A and s_B so $\delta_{AB}(S)$ will always contain the computation time of E and the position of E in the schedule does not modify $\delta_{AB}(S)$.

Because $E \in \bigcup_{H \in \Gamma_{CD}^-(A;B)} \mathcal{M}(A, H)$ there is no operation $F \in \mathcal{M}(C, D)$ which must be scheduled before E . So E may be scheduled before C . If we schedule any operation $E \in \bigcup_{H \in \Gamma_{CD}^-(A;B)} \mathcal{M}(A, H)$ after C it is obvious that for some schedule S $\delta_{CD}(S)$ is increased with the sum of computation times of these operations E . The lemma is proved \square

Lemma 4 We have system given by graph $G = (V, E)$ such that all paths, on which lency constraints are imposed, are in relation X . For $(A, B) X (C, D)$ and some schedule S with $s_D \prec s_B$, if all operations $E \in \bigcup_{H \in \Gamma_{CD}^+(A;B)} \mathcal{M}(H, B)$ are scheduled between

s_D and s_B , then $\delta_{AB}(S)$ is not modified compared with the case when the last operation $E \in \bigcup_{H \in \Gamma_{CD}^+(A;B)} \mathcal{M}(H, B)$ is scheduled before s_D . Also, if the last operation $E \in \bigcup_{H \in \Gamma_{CD}^+(A;B)} \mathcal{M}(H, B)$ is scheduled before s_D , then $\delta_{CD}(S)$ is increased compared with the

case when all operations $E \in \bigcup_{H \in \Gamma_{CD}^+(A;B)} \mathcal{M}(H, B)$ are scheduled between s_D and s_B .

Proof Because use $E = \bigcup_{H \in \Gamma_{CD}^+(\mathbf{A}; \mathbf{B})} \mathcal{M}(H, B)$ is always scheduled between $s_{\mathbf{A}}$ and $s_{\mathbf{B}}$ so $\delta_{\mathbf{AB}}(S)$ will always contain in the computation time of E and the position of E in the schedule does not modify $\delta_{\mathbf{AB}}(S)$. Because use $E = \bigcup_{H \in \Gamma_{CD}^+(\mathbf{A}; \mathbf{B})} \mathcal{M}(H, B)$ there is no operation $F = \mathcal{M}(C, D)$ which must be scheduled after E . So D may be scheduled before all operations $E = \bigcup_{H \in \Gamma_{CD}^+(\mathbf{A}; \mathbf{B})} \mathcal{M}(H, B)$. If we schedule any operation $E = \bigcup_{H \in \Gamma_{CD}^+(\mathbf{A}; \mathbf{B})} \mathcal{M}(H, B)$ before D it is obvious that for some schedule S $\delta_{\mathbf{CD}}(S)$ is increased with the sum of computation times of these operations E . The lemma is proved \square

Theorem 4 Let $\mathcal{G} = (\mathcal{P}, \mathcal{E})$ be a graph defining a graph and there are two latency constraints imposed on the pairs (A, B) and (C, D) , where $(A, B) \times (C, D)$. The two latency constraints are not equal to the sum of execution times of operations belonging to the constraint. The system is schedulable if and only if

$$\begin{cases} L_{\mathbf{AB}} & \sum_{H \in \mathcal{M}(\mathbf{A}; \mathbf{B})} C_{\mathbf{H}} + \sum_{H \in \bigcup_{E \in \text{ft}_{AB}(C, D)} \mathcal{M}(\mathbf{E}; \mathbf{D})} C_{\mathbf{H}} \\ L_{\mathbf{CD}} & \sum_{H \in \mathcal{M}(\mathbf{C}; \mathbf{D})} C_{\mathbf{H}} + \sum_{H \in \bigcup_{E \in \text{lt}_{CD}(A, B)} \mathcal{M}(\mathbf{A}; \mathbf{E})} C_{\mathbf{H}} \end{cases} \quad (8)$$

or

$$\begin{cases} L_{\mathbf{CD}} & \sum_{H \in \mathcal{M}(\mathbf{C}; \mathbf{D})} C_{\mathbf{H}} + \sum_{H \in \bigcup_{E \in \text{ft}_{CD}(A, B)} \mathcal{M}(\mathbf{E}; \mathbf{B})} C_{\mathbf{H}} \\ L_{\mathbf{AB}} & \sum_{H \in \mathcal{M}(\mathbf{A}; \mathbf{B})} C_{\mathbf{H}} + \sum_{H \in \bigcup_{E \in \text{lt}_{AB}(C, D)} \mathcal{M}(\mathbf{C}; \mathbf{E})} C_{\mathbf{H}} \end{cases} \quad (9)$$

Proof The proof is made by double implication.

First we prove that if the system is schedulable then 8 or 9 are satisfied. Because use the system is schedulable then there is at least one schedule S satisfying all constraints. For this schedule A is scheduled before or after C .

Because we are in the case of latency constraints which are not equal to the sum of execution times of operations belonging to the constraint when A is scheduled before C B is scheduled before D (see figure 13).

Using lemma 3 because use A is scheduled before C then all operations $E = \bigcup_{H \in \Gamma_{CD}^-(\mathbf{A}; \mathbf{B})} \mathcal{M}(A, H)$

are scheduled between $s_{\mathbf{A}}$ and $s_{\mathbf{C}}$. We obtain

$$L_{\mathbf{AB}} \sum_{H \in \mathcal{M}(\mathbf{A}; \mathbf{B})} C_{\mathbf{H}} + \sum_{H \in \bigcup_{E \in \text{ft}_{AB}(C, D)} \mathcal{M}(\mathbf{E}; \mathbf{D})} C_{\mathbf{H}} \quad (10)$$

Using lemma 4 because B is scheduled before D then all operations $E \in \bigcup_{H \in \Gamma_{AB}^+(\mathbf{C};\mathbf{D})} \mathcal{M}(H, D)$ are scheduled before $s_{\mathbf{D}}$. We obtain

$$L_{\mathbf{CD}} = \sum_{H \in \mathcal{M}(\mathbf{C};\mathbf{D})} C_H + \sum_{H \in \bigcup_{E \in \text{It}_{\mathbf{CD}}(\mathbf{A},\mathbf{B})} \mathcal{M}(\mathbf{A};\mathbf{E})} C_H \quad (11)$$

From 10 and 11 we obtain that 8 is satisfied.

Because we are in the case of l tency constraints which are not equal to the sum of execution times of operations belonging to the constraint when A is scheduled after C B is scheduled after D (see figure 14) and the proof follows the same principles as for the first case in order to prove that 9 is satisfied. The direct implication is proved.

We prove now that if 8 or 9 is satisfied then the system is schedulable. The idea of this proof is to build a schedule which satisfies the l tency constraints. First we suppose that 8 is satisfied. We consider the schedule given in figure 13 with all operations $E \in \bigcup_{H \in \Gamma_{AB}^+(\mathbf{C};\mathbf{D})} \mathcal{M}(H, D)$ scheduled before $s_{\mathbf{D}}$ and all operations $E \in \bigcup_{H \in \Gamma_{CD}^-(\mathbf{A};\mathbf{B})} \mathcal{M}(A, H)$ scheduled between $s_{\mathbf{A}}$ and $s_{\mathbf{C}}$. Because of 8 this schedule satisfies the l tency constraints.

We suppose that 9 is satisfied. The proof follows the same principles as before using the schedule given in figure 14 in order to prove that the system is schedulable. The theorem is proved \square

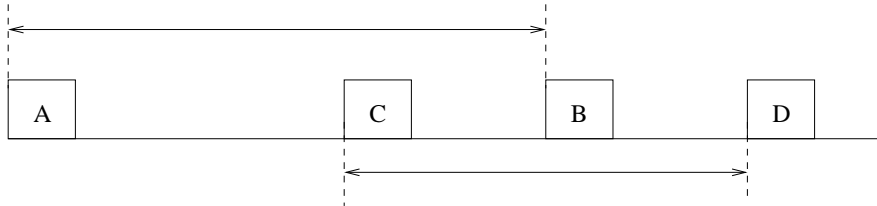


Figure 13 Schedule illustrating theorem 4

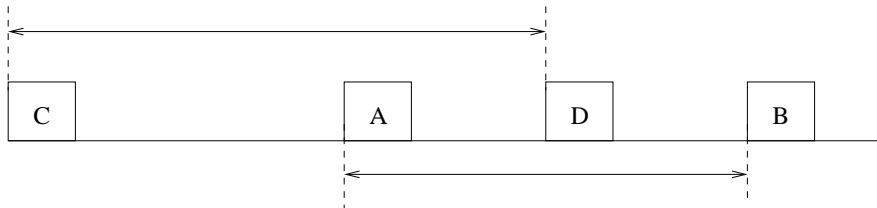


Figure 14 Schedule illustrating theorem 4

Remark 7 for the case studied by theorem 4 the minimal sets corresponding to the two latency constraints do not contain only operations belonging to the latency constraint but also operations belonging to the other latency constraint. The example 3 illustrates such sets.

Theorem 5 Let $\mathcal{G} = (\mathcal{G}, \mathcal{E})$ be a graph defining a system and processors, on which latency constraints are imposed, a relation X . The system is schedulable if and only if, for each pair (A, B) on which a latency constraint is imposed, and which is in relation X with processors (C_i, D_i) , $i = 1, 2, \dots, n$, on which latency constraints are imposed, we have

$$L_{AB} \leq \sum_{H \in \mathcal{W}} C_H \quad (12)$$

where:

$$\begin{aligned} \mathcal{W} = & \mathcal{M}(A, B) \cup \bigcup_{i \in \{1, \dots, j\}; E \in \text{lt}_{AB}(C_i, D_i)} \mathcal{M}(C_i, E) \cup \bigcup_{i \in \{j+1, \dots, k\}; E \in \text{ft}_{AB}(C_i, D_i)} \mathcal{M}(E, D_i) \cup \\ & \bigcup_{i \in \{k+1, \dots, m\}} \mathcal{M}(C_i, D_i), \end{aligned}$$

where $j < k < m < n$ are the natural numbers for which the following relations are satisfied:

$$\begin{aligned} L_{C_i, D_i} & \leq \sum_{H \in \{\mathcal{M}(C_i, D_i) \cup \bigcup_{E \in \text{ft}_{C_i, D_i}(AB)} \mathcal{M}(E, B)\}} C_H, \quad i = 1, \dots, j \\ L_{C_i, D_i} & \leq \sum_{H \in \{\mathcal{M}(C_i, D_i) \cup \bigcup_{E \in \text{lt}_{C_i, D_i}(A; B)} \mathcal{M}(A, E)\}} C_H, \quad i = j+1, \dots, k \\ L_{C_i, D_i} & \leq \sum_{H \in \mathcal{M}(C_i, D_i)} C_H, \quad i = k+1, \dots, m \quad \text{and} \quad L_{C_i, D_i} \leq \sum_{H \in \{\mathcal{M}(C_i, D_i) \cup \mathcal{M}(A; B)\}} C_H, \\ & i = m+1, \dots, n. \end{aligned}$$

Proof The proof is made by double implication. First we prove the direct implication. We have that the system is schedulable which means there is a schedule S which satisfies all the latency constraints $s_B - s_A + C_B \leq L_{AB} = L(A, B)$. But $s_B - s_A + C_B$ is the sum of computation times of operations which are scheduled from s_A to s_B . Because of the partial order the set of the operations scheduled from s_A to s_B contains at least some operations belonging to $\mathcal{M}(C_i, D_i)$, $i = 1, 2, \dots, n$. The operations of $\mathcal{M}(C_i, D_i)$ which are scheduled from s_A to s_B are given by scheduling order of operations $C_i, D_i, A, B, i = 1, 2, \dots, n$ in schedule S . Therefore we have to study all the possible orders for these two pairs of operations i.e. six orders such that A is always scheduled before B and C before D . Also among the six orders because (A, B) is in relation X with (C_i, D_i) the orders $s_A + C_A \leq s_B + C_B \leq s_{C_i} + C_{C_i} \leq s_{D_i} + C_{D_i}$ and $s_{C_i} + C_{C_i} \leq s_{D_i} + C_{D_i}$ and $s_A + C_A \leq s_B + C_B \leq s_{C_i} + C_{C_i} \leq s_{D_i} + C_{D_i}$ are forbidden. It remains 4 possible cases for scheduling the pairs (A, B) and (C_i, D_i) , $i = 1, 2, \dots, n$.

1. $s_{\mathbf{A}} + C_{\mathbf{A}} \quad s_{\mathbf{C}_i} + C_{\mathbf{C}_i} \quad s_{\mathbf{B}} + C_{\mathbf{B}} \quad s_{\mathbf{D}_i} + C_{\mathbf{D}_i}, \quad i = 1, 2, \dots, j$;
2. $s_{\mathbf{C}_i} + C_{\mathbf{C}_i} \quad s_{\mathbf{A}} + C_{\mathbf{A}} \quad s_{\mathbf{D}_i} + C_{\mathbf{D}_i} \quad s_{\mathbf{B}} + C_{\mathbf{B}}, \quad i = j, \dots, k$;
3. $s_{\mathbf{C}_i} + C_{\mathbf{C}_i} \quad s_{\mathbf{A}} + C_{\mathbf{A}} \quad s_{\mathbf{B}} + C_{\mathbf{B}} \quad s_{\mathbf{D}_i} + C_{\mathbf{D}_i}, \quad i = k + 1, \dots, m$;
4. $s_{\mathbf{A}} + C_{\mathbf{A}} \quad s_{\mathbf{C}_i} + C_{\mathbf{C}_i} \quad s_{\mathbf{D}_i} + C_{\mathbf{D}_i} \quad s_{\mathbf{B}} + C_{\mathbf{B}}, \quad i = m + 1, \dots, n$;

Bec use of lemm 3 the c se 1 implies th t ll oper tions belonging to $\mathcal{M}(A, E), E \Gamma_{\mathbf{C}_i; \mathbf{D}_i}^-(AB), i = 1, 2, \dots, j$ re scheduled from A to C . Consequently bec use C_i is scheduled before B the rest of oper tions belonging to $\mathcal{M}(A, B)$ i.e. oper tions belonging to $\mathcal{M}(E, B), E ft_{\mathbf{C}_i; \mathbf{D}_i}(A, B)$ re scheduled between C_i nd $D_i, i = 1, 2, \dots, j$.

Bec use of lemm 4 the c se 1 implies th t ll oper tions belonging to $\mathcal{M}(E, D_i), E \Gamma_{\mathbf{A}\mathbf{B}}^+(C_i, D_i), i = 1, 2, \dots, j$ re scheduled from B to D_i . Consequently bec use C_i is scheduled before B the rest of oper tions belonging to $\mathcal{M}(C_i, D_i)$ i.e. oper tions belonging to $\mathcal{M}(C_i, E), E lt_{\mathbf{A}\mathbf{B}}(C_i, D_i)$ re scheduled between A nd B .

Bec use of lemm 3 the c se 2 implies th t ll oper tions belonging to $\mathcal{M}(C_i, E), E \Gamma_{\mathbf{A}\mathbf{B}}^-(C_i, D_i), i = j + 1, \dots, k$ re scheduled from C_i to A . Consequently bec use A is scheduled before D_i the rest of oper tions belonging to $\mathcal{M}(C_i, D_i)$ i.e. oper tions belonging to $\mathcal{M}(E, D_i), E ft_{\mathbf{A}\mathbf{B}}(C_i, D_i)$ re scheduled between A nd B .

Bec use of lemm 4 the c se 2 implies th t ll oper tions belonging to $\mathcal{M}(E, B), E \Gamma_{\mathbf{C}_i; \mathbf{D}_i}^+(A, B), i = j + 1, \dots, k$ re scheduled from C_i to D_i . Consequently bec use A is scheduled before D_i the rest of oper tions belonging to $\mathcal{M}(A, B)$ i.e. oper tions belonging to $\mathcal{M}(A, E), E lt_{\mathbf{C}_i; \mathbf{D}_i}(A, B)$ re scheduled between C nd D .

The c se 3 implies th t ll oper tions belonging to $\mathcal{M}(C_i, D_i), i = k + 1, \dots, m$ re scheduled from A to B . The c se 3 does not llow to s y if oper tions belonging to $\mathcal{M}(A, B)$ re scheduled from C_i to D_i .

The c se 4 implies th t ll oper tions belonging to $\mathcal{M}(A, B)$ re scheduled from C_i to $D_i, i = m + 1, \dots, n$. The c se 4 does not llow to s y if oper tions belonging to $\mathcal{M}(C_i, D_i)$ re scheduled from A to B .

In conclusion the set of oper tions which re scheduled from A to B cont ins t le st the oper tions belonging to

$$= \mathcal{M}(A, B) \cup \bigcup_{\mathbf{i} \in \{1; \dots; j\}; \mathbf{E} \in lt_{\mathbf{A}\mathbf{B}}(\mathbf{C}_i; \mathbf{D}_i)} \mathcal{M}(C_i, E) \cup \bigcup_{\mathbf{i} \in \{j+1; \dots; k\}; \mathbf{E} \in ft_{\mathbf{A}\mathbf{B}}(\mathbf{C}_i; \mathbf{D}_i)} \mathcal{M}(E, D_i) \cup \bigcup_{\mathbf{i} \in \{k+1; \dots; m\}} \mathcal{M}(C_i, D_i) \text{ where}$$

$$j, k, m \in \mathbb{N} \text{ re the n tur l numbers for which the following rel tions re s tisfied}$$

$$s_{\mathbf{D}_i} \leq s_{\mathbf{C}_i} + C_{\mathbf{D}_i} \quad \sum_{\mathbf{H} \in \{\mathcal{M}(\mathbf{C}_i; \mathbf{D}_i) \cup \bigcup_{\mathbf{E} \in ft_{\mathbf{C}_i; \mathbf{D}_i}(\mathbf{A}; \mathbf{B})} \mathcal{M}(E, B)\}} C_{\mathbf{H}} \quad i = 1, \dots, j$$

$$\begin{aligned}
 s_{\mathbf{D}_i} &= s_{\mathbf{C}_i} + C_{\mathbf{D}_i} + \sum_{\mathbf{H} \in \{\mathcal{M}(\mathbf{C}_i; \mathbf{D}_i) \cup \bigcup_{\mathbf{E} \in \text{lt}_{C_i, D_i}(\mathbf{A}; \mathbf{B})} \mathcal{M}(A, E)\}} C_{\mathbf{H}} \quad i = j+1, \dots, k \\
 s_{\mathbf{D}_i} &= s_{\mathbf{C}_i} + C_{\mathbf{D}_i} + \sum_{\mathbf{H} \in \mathcal{M}(\mathbf{C}_i; \mathbf{D}_i)} C_{\mathbf{H}} \quad i = k+1, \dots, m \text{ and} \\
 s_{\mathbf{D}_i} &= s_{\mathbf{C}_i} + C_{\mathbf{D}_i} + \sum_{\mathbf{H} \in \{\mathcal{M}(\mathbf{C}_i; \mathbf{D}_i) \cup \bigcup_{\mathbf{E} \in \mathcal{M}(\mathbf{A}; \mathbf{B})} C_{\mathbf{H}}\}} C_{\mathbf{H}} \quad i = m+1, \dots, n.
 \end{aligned}$$

Using $L(A, B) = s_{\mathbf{D}_i} - s_{\mathbf{C}_i} + C_{\mathbf{D}_i}$ we obtain inequality (12). The direct implication is proved.

We prove the inverse implication. We have inequality (12) satisfied for each pair (A, B) on which precedence constraint is imposed. This means that we may schedule from A to B the operations belonging to

$$\begin{aligned}
 &= \mathcal{M}(A, B) \cup \bigcup_{\mathbf{i} \in \{1; \dots; j\}; \mathbf{E} \in \text{lt}_{AB}(\mathbf{C}_i; \mathbf{D}_i)} \mathcal{M}(C_i, E) \cup \bigcup_{\mathbf{i} \in \{j+1; \dots; k\}; \mathbf{E} \in \text{ft}_{AB}(\mathbf{C}_i; \mathbf{D}_i)} \mathcal{M}(E, D_i) \cup \\
 &\bigcup_{\mathbf{i} \in \{k+1; \dots; n\}} \mathcal{M}(C_i, D_i).
 \end{aligned}$$

The set contains all the operations belonging to $\mathcal{M}(C_i, D_i) \quad i = 1, \dots, n$ which must be scheduled from A to B in order to satisfy the partial order. Using inequality (12) for each pair (A, B) we obtain a schedule which satisfies the partial order. Because precedence constraints are already satisfied by inequality (12) the system is schedulable. The inverse implication is proved and the theorem is proved \square

Remark 8 *The theorem 5 presents schedulability conditions which allows to obtain minimal sets corresponding to the precedence constraints. Because building these sets for general case is probably NP-hard problem, we will consider from now on only cases where each precedence constraint is in relation X with at most one precedence constraint. For this case in the next section we give polynomial scheduling algorithm.*

We give an example of a system with precedence constraints in relation X .

Example 6 *Let $G = (V, \mathcal{E})$ be the graph given in figure 15 with the execution times $C_{\mathbf{A}} = 1$, $A \rightarrow C$ and the precedence constraints $L_{\mathbf{AC}} = 3$, $L_{\mathbf{DF}} = 9$ and $L_{\mathbf{HJ}} = 5$. We have that $(A, C) X (D, F)$ and $(D, F) X (H, J)$. The schedulability conditions are satisfied and the figure 16 gives a schedule which satisfies all constraints.*

4.4 General schedulability condition

Giving general schedulability condition amounts to prove that there is a schedule which satisfies all the precedence constraints if and only if each precedence constraint in relation \parallel_Z or X with other precedence constraints is satisfied. Previously we obtained separately schedulability condition for systems with all pairs in relation \parallel and Z and schedulability condition for

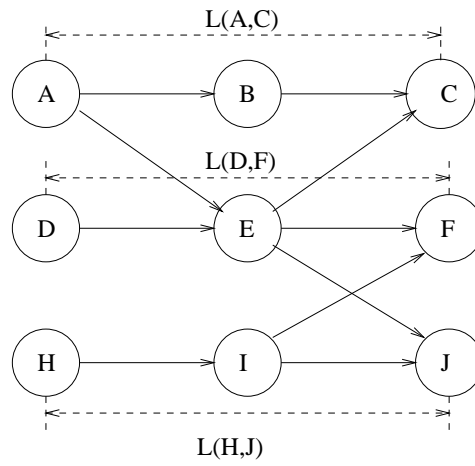


Figure 15 System with latency constraints in relation X

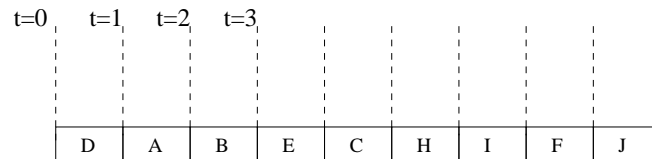


Figure 16 Schedule satisfying all constraints

systems with all pirs in relation X . From now on we will study only the schedulability condition of systems with all lency constraint $L_{\mathbf{X};\mathbf{Y}}$ greater than the sum of computation times of operations belonging to $\mathcal{M}(X, Y)$ because the systems which do not satisfy this latter condition are obviously not schedulable. The following theorem gives the general schedulability condition.

Because all lency constraint $L_{\mathbf{X};\mathbf{Y}}$ is greater than the sum of computation times of operations belonging to $\mathcal{M}(X, Y)$. Because of lemma 1 we have that a schedule in which between s_A and s_B there are no operation belonging to pirs in relation \parallel or Z with (A, B) does not satisfy the lency constraints with all pirs in relation \parallel and X on which lency constraints are imposed we proved that a system with all the lency constraints well-defined is always schedulable. This remains true for the general case: the general schedulability condition will concern only pirs of operations which are in relation.

Theorem 6 Let $\mathcal{G} = (\mathcal{G}, \mathcal{E})$ be a graph defining a system and \mathcal{L} a set of lency constraints imposed on pirs of operations. There is a schedule satisfying all the lency constraints if and only if inequality (12) is satisfied for each piri (A, B) in relation X with n pirs (C_i, D_i) , $i = 1, 2, \dots, n$.

Proof The proof is made by double implication and follows the same principles as the proof of theorem 5. The direct implication assumes that the system is schedulable and proves that inequality (12) is satisfied taking into account for each piri on which lency constraint is imposed all pirs such that this piri is in relation \parallel , Z or X . The inverse implication builds a schedule which satisfies all lency constraints using inequality (12) \square

Remark 9 For a system with n lency constraints, the number of inequalities of type (12) which must be verified is at most $n(n-1)$.

Example 7 For the graph of figure 17, we have all computation times equal to 1, $C_A = 1$, A is a piri. The following lency constraints are imposed: $L_{AB} = 7$, $L_{CD} = 12$, $L_{MF} = 3$ and $L_{OR} = 4$. Note that $(A, B)X(C, D)$, $(A, B)Z(M, F)$, $(C, D)X(M, F)$ and (O, R) is in relation \parallel with all the other lency constraints. First, note that all lency constraints $L_{\mathbf{X};\mathbf{Y}}$ are greater than the sum of computation times of operations belonging to $\mathcal{M}(X, Y)$. Then applying theorem 6, the system is schedulable if and only if the following relations are satisfied:

$$L_{AB} = \sum_{\mathbf{X} \in \{\mathcal{M}(A;B) \cup \bigcup_{\mathbf{Y} \in \text{ft}_{AB}(C;D)} \mathcal{M}(C, Y)\}} C_{\mathbf{X}}$$

$$L_{CD} = \sum_{\mathbf{X} \in \{\mathcal{M}(C;D) \cup \bigcup_{\mathbf{Y} \in \text{ft}_{CD}(A;B)} \mathcal{M}(Y, B) \cup \mathcal{M}(M, F)\}} C_{\mathbf{X}}$$

$$L_{MF} = \sum_{\mathbf{X} \in \mathcal{M}(M;F)} C_{\mathbf{X}}$$

We obt in:

$$\begin{cases} L_{AB} & C_A + C_G + C_H + C_I + C_B + C_C + C_K \\ L_{CD} & C_C + C_I + C_J + C_K + C_L + C_D + C_M + \\ & C_N + C_F + C_H + C_B \\ L_{MF} & C_M + C_N + C_F \end{cases}$$

Bec use ll three inequ tions re veri ed, the system is schedul ble. Indeed the schedule $S = s_O \ s_P \ s_R \ s_E \ s_A \ s_G \ s_C \ s_K \ s_I \ s_H \ s_B \ s_M \ s_N \ s_F \ s_J \ s_L \ s_D$ s tis es ll the l tency constr ints. In the following section we give n lgorithm which llows to obt in schedule which s tis es ll the l tency constr ints for the c se where e ch l tency constr int is in rel tion X with t most one l tency constr int.

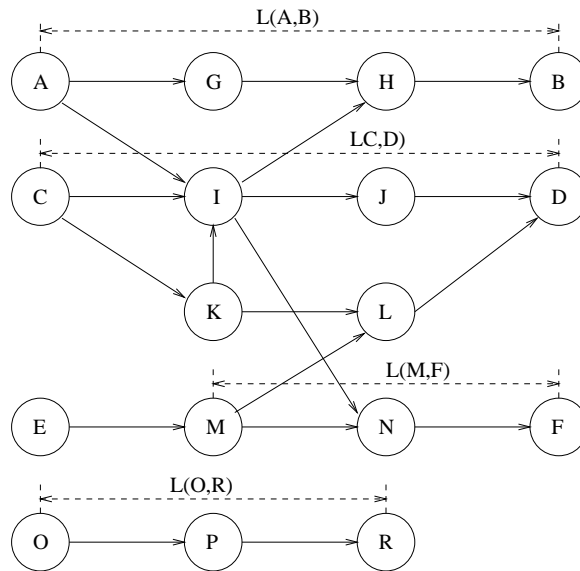


Figure 17 Ex mple for gener l schedul bility condition

5 Optimal scheduling algorithm

This section presents n optim l scheduling lgorithm for the c se where e ch l tency constr int is in rel tion X with t most one l tency constr int. This lgorithm builds schedules s tisfying the schedul bility condition obt ined in the previous section.

A scheduling lgorithm tr nsforms the p rti l order defined by the gr ph in tot l order (one of possibles tot l orders) which s tisfies the l tency constr ints. In our c se the

scheduling algorithm 2 is applied only to the pattern and it uses algorithm 1 that we call “marking operations algorithm”. This algorithm “anticipates” which operations are the most important for the latency constraints.

We denote by $G = (V, \mathcal{E})$ the oriented cyclic graph-pattern where V is the set of operations and \mathcal{E} is the set of edges and by $\mathcal{D}(A) = \{B \mid \text{there is a path from } A \text{ to } B\}$. We denote by \mathcal{W} the working-set used during the algorithm.

The purpose of the marking algorithm is to associate to each operation A a mark which indicates if an operation C belonging to a pair (B, C) with latency constraint will be scheduled after A . This is possible thanks to the existence of at least one path between A and C and to the non-existence of any path between A and B . If for an operation there are several operations satisfying this property then the mark is equal to the smallest latency constraint. We denote this mark by $mark(A) \in \mathbb{N}^* \cup \{\infty\}$ where ∞ is a positive integer greater than any other number belonging to \mathbb{N}^* . These marks may change their values during the marking algorithm. This latter is applied only on the pattern of the graph like the scheduling algorithm.

Algorithm 1

Initialisation if (A, B) has latency constraint $L(A, B)$ then $mark(B) = L(A, B)$ and $mark(A) = \infty$ else $mark(A) = mark(B) = \infty$. Moreover if B belongs to several pairs with latency constraints then $mark(B) = \min_{(C, B) \in \mathcal{L}} L(C, B)$ and $mark(A) = \infty$. Let $\mathcal{W} = \mathcal{L}$.

Step 1 for $(A, B) \in \mathcal{W}$ and for each operation $C \in V \setminus \{A, B\}$ there are three possibilities

- (a) if $A \in \mathcal{D}(C)$ then $mark(C) = mark(A)$;
- (b) if $A \notin \mathcal{D}(C)$ and $B \in \mathcal{D}(C)$ then $mark(C) = \min(mark(A), mark(B))$;
- (c) if $A \notin \mathcal{D}(C)$ and $B \notin \mathcal{D}(C)$ then $mark(C) = mark(C)$.

Let $\mathcal{W} = \mathcal{W} \setminus \{(A, B)\}$.

Step 2 if $\mathcal{W} = \emptyset$ then goto Step 1 else the algorithm stops.

We denote by \mathcal{L}_X the set of latency constraints which are in relation X with other latency constraints and which do not have the difference between the value of the latency and the sum of operations belonging to the pair is equal to 0. Without any loss of generality we consider this set ordered i.e. if $L(A, B)$ is before $L(C, D)$ in \mathcal{L}_X then $L_{AB} < L_{CD}$.

The scheduling algorithm uses the marks obtained using the marking algorithm. We denote by \mathcal{W} the working set by s_{τ} the start time of the first scheduled operation by C_{τ} its execution time and by $Prec(A)$ the set of predecessors of operation A . During the application of the algorithm the set contains the available operations. We notice that between two operations which are available in the same time there is no path. Also during the application of the algorithm each time that an operation is scheduled s_{τ} (respectively C_{τ}) is replaced by the start time (execution time) of this operation.

Algorithm 2

Initialisation $\mathcal{W} = \bigcup_{\mathbf{A} \in \mathcal{V}} \text{and } \mathbf{P}_{\text{rec}(\mathbf{A})=\emptyset} \mathbf{A}$ and $s_{\mathbf{T}} = 0, C_{\mathbf{T}} = 0$.

Step 1 (*operation with l tency constraint*)

if $\mathcal{W} = \emptyset$ then return \mathcal{W} when we chose A such that

$$\text{mark}(A) = \min_{\mathbf{B} \in \mathcal{W}} \text{mark}(B)$$

If $L(C_1, D_1) \in \mathcal{L}_{\mathbf{X}}$ and $L(C_i, D_i) \in \mathcal{L}_{\mathbf{X}}, i = 2, 3, \dots, n$ such that $A = \bigcup_{\mathbf{E} \in \Gamma_{C_i, D_i}^+(\mathbf{C}_1, \mathbf{D}_1)} \mathcal{M}(E, D_1)$, $i = 2, 3, \dots, n$ then let $B = \bigcup_{\mathbf{E} \in \Gamma_{C_1, D_1}^+(\mathbf{C}_i, \mathbf{D}_i)} \mathcal{M}(E, D_i)$. If the operation B exists then $s_{\mathbf{B}} = s_{\mathbf{T}} + C_{\mathbf{T}}$ we remove B from \mathcal{W} all operations which become available added to \mathcal{W} and we go to step 4. If the operation B does not exist then $s_{\mathbf{A}} = s_{\mathbf{T}} + C_{\mathbf{T}}$ we remove A from \mathcal{W} all operations which become available added to \mathcal{W} and we go to Step 4.

Step 2 (*operation which is not first in l tency constraint*)

if $\mathcal{W} = \emptyset$ then return \mathcal{W} if $A \in \mathcal{W}$ such that there is no operation $B \in \mathcal{W}$ with $(A, B) \in \mathcal{L}$ then $s_{\mathbf{A}} = s_{\mathbf{T}} + C_{\mathbf{T}}$ we remove it from \mathcal{W} all operations which become available added to \mathcal{W} and we go to Step 4.

Step 3 (*operation which is first in l tency constraint*)

if $\mathcal{W} = \emptyset$ then return \mathcal{W} if $A \in \mathcal{W}$ such that there is $B \in \mathcal{W}$ $\text{vec}(A, B) \in \mathcal{L}$ then $s_{\mathbf{A}} = s_{\mathbf{T}} + C_{\mathbf{T}}$ with $L(A, B) = \max_{(\mathbf{C}; \mathbf{D}) \in \mathcal{L} \text{ et } \mathbf{C} \in \mathcal{W}} L(\mathbf{C}, \mathbf{D})$ we remove it from \mathcal{W} all operations which become available added to \mathcal{W} and we go to Step 4.

Step 4

if $\mathcal{W} = \emptyset$ then the algorithm stops else we go to Step 1.

The scheduling algorithm 2 is proved optimal for the case where each l tency constraint is in relation \mathbf{X} with at most one l tency constraint. Before proving this optimality we give an example of schedule obtained with this algorithm.

Example 8 Let $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ be the graph given in figure 1 with $C_{\mathbf{A}} = 2, C_{\mathbf{B}} = 1$ and $C_{\mathbf{C}} = 2$ and the l tency constraints $L(A_2, C_2) = 10$ and $L(B, C_1) = 9$. After applying the marking algorithm we obtain the marks given in table 1 where $m(A)$ denotes $\text{mark}(A)$.

We obtain the table 2 using the scheduling algorithm 2.

Theorem 7 The scheduling algorithm 2 is optimal (if there is a schedule which satisfies the constraints then the algorithm will find it).

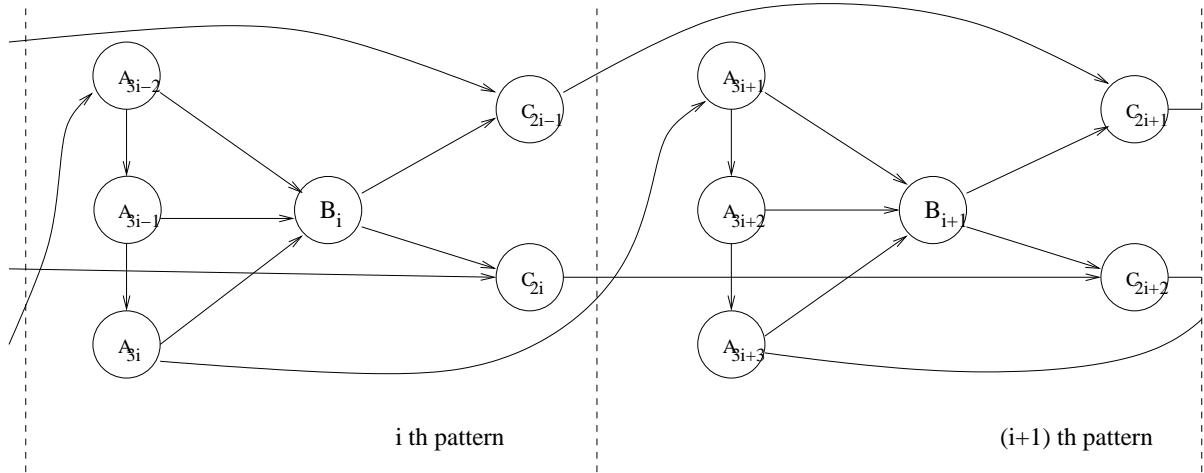


Figure 18 Graph illustrating the scheduling algorithm 2

	$m(A_1)$	$m(A_2)$	$m(A_3)$	$m(B)$	$m(C_1)$	$m(C_2)$
Initiation					9	10
$L(B, C_1)$					9	10
$L(A_2, C_2)$			10	10	9	10

Table 1 Marks obtained using the marking algorithm

	s_T	C_T	Step used	utilisé	Choice
A_1	0	0	Step 2		$s_{A_1} = 0$
A_2	0	2	Step 3		$s_{A_2} = 2$
A_3	2	2	Step 1		$s_{A_3} = 4$
B	4	2	Step 1		$s_B = 6$
C_1, C_2	6	1	Step 1		$s_{C_2} = 7$
C_1	7	2	Step 1		$s_{C_1} = 9$

Table 2 Schedule obtained using the algorithm 2

Proof We prove that the scheduling algorithm builds 2 schedules which satisfy the schedulability conditions and if these schedules do not satisfy the constraints then no other will. The proof has three parts – first one concerning the latency constraints imposed on pairs

in relation \parallel second part concerning the l tency constr ints imposed on p irs in relation Z and first part concerning the l tency constr ints imposed on p irs in relation X .

Without loss of generality we consider that all l tency constr ints have different values.

Let $L(A, B)$ and $L(C, D)$ be some two l tency constr ints imposed on p irs in relation \parallel . Because there is no path from operation belonging to (A, B) to operation belonging to (C, D) then the mark of operations belonging to (A, B) is not modified by the l tency constraint $L(C, D)$. Likewise because there is no path from operation belonging to (C, D) to operation belonging to (A, B) then the mark of operations belonging to (C, D) is not modified by the l tency constraint $L(A, B)$. Therefore the operations belonging to the two p irs have different marks and they will be scheduled either in the following order $s_A + C_A < s_B + C_B < s_C + C_C < s_D + C_D$ either in the order $s_C + C_C < s_D + C_D < s_A + C_A < s_B + C_B$. The two orders lead to the schedulability condition for the case of l tency constraints imposed on p irs in relation \parallel .

Let $L(A, B)$ and $L(C, D)$ be some two l tency constraints imposed on p irs which are in relation Z . Because there is no path from operation belonging to (C, D) to operation belonging to (A, B) then the mark of operations belonging to (C, D) is not modified by the l tency constraint $L(A, B)$. Because there is a path from operation belonging to (A, B) to the latest operation belonging to (C, D) then the mark of A may be modified by the l tency constraint $L(C, D)$ only if $L_{AB} > L_{CD}$. In this case the operations belonging to the two p irs will be scheduled in the following order $s_A + C_A < s_B + C_B < s_C + C_C < s_D + C_D$. In the opposite case the mark of A is not modified by the l tency constraint $L(C, D)$ and the operations belonging to the two p irs will be scheduled either in this order $s_A + C_A < s_B + C_B < s_C + C_C < s_D + C_D$ either in this order $s_C + C_C < s_D + C_D < s_A + C_A < s_B + C_B$. The two orders lead to the schedulability condition for the case of l tency constraints imposed on p irs in relation Z .

Let $L(A, B)$ and $L(C, D)$ be some two l tency constraints imposed on p irs which are in relation X . Because there is a path from operation belonging to (A, B) to the latest operation belonging to (C, D) then the mark of A may be modified by the l tency constraint $L(C, D)$ only if $L_{AB} > L_{CD}$. In this case the existence of a path between operations belonging to (C, D) to the latest operation belonging to (A, B) does not this mark. Likewise we obtain the same conclusion if $L_{AB} < L_{CD}$.

For the three cases the schedulability conditions are satisfied by the schedules obtained using the algorithm 2. The theorem is proved \square

6 Conclusion and future work

We give a schedulability condition for systems with l tency and precedence constraints using the model based on graphs presented in [5]. This result is obtained by studying three relations \parallel , Z and X between p irs of operations and by studying the l tency constraints imposed on the p irs of operations satisfying the latter relations.

We give a scheduling algorithm which is proved optimal for the case where the l tency constraints are in X with at most one other l tency constraint.

Presently we study the complexity of the scheduling problem for the case where the latency constraints may be in X with at least one other latency constraint. We plan to generalise this schedulability condition to real-time systems with precedence periodicity and latency constraints.

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